

# Current Developments in Tooling and Editor Support in textX

Milan Šović, Daniel Elero & Igor Dejanović  
University of Novi Sad



# Agenda

- textX
- Web Playground
- VS Code Extension
- Drone Example Demo
- Summary
- Q&A

JGBX



# textX

Overview, Basic Concepts & textX CLI



- Meta-Language for DSL specification in Python
- Inspired by Xtext
- Project started by Igor Dejanović in 2014
- 24 contributors
- Current version – 4.0.1

GitHub: <https://github.com/textX/textX>

PyPi: <https://pypi.org/project/textX/>

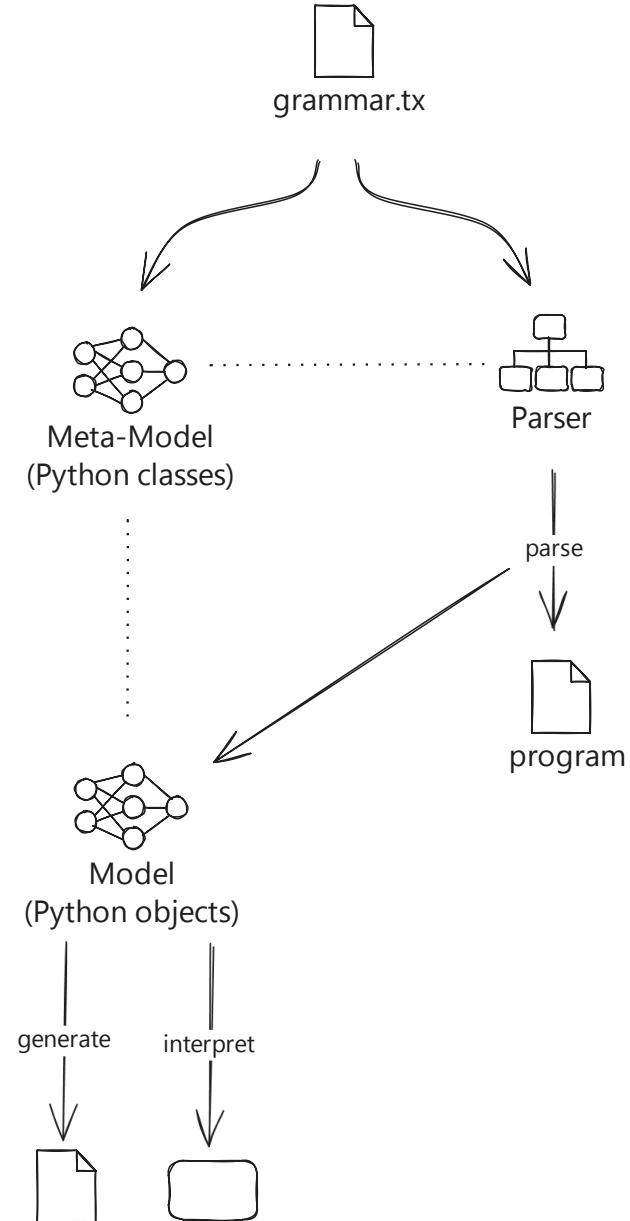
Docs: <https://textx.github.io/textX>



# textX – Overview

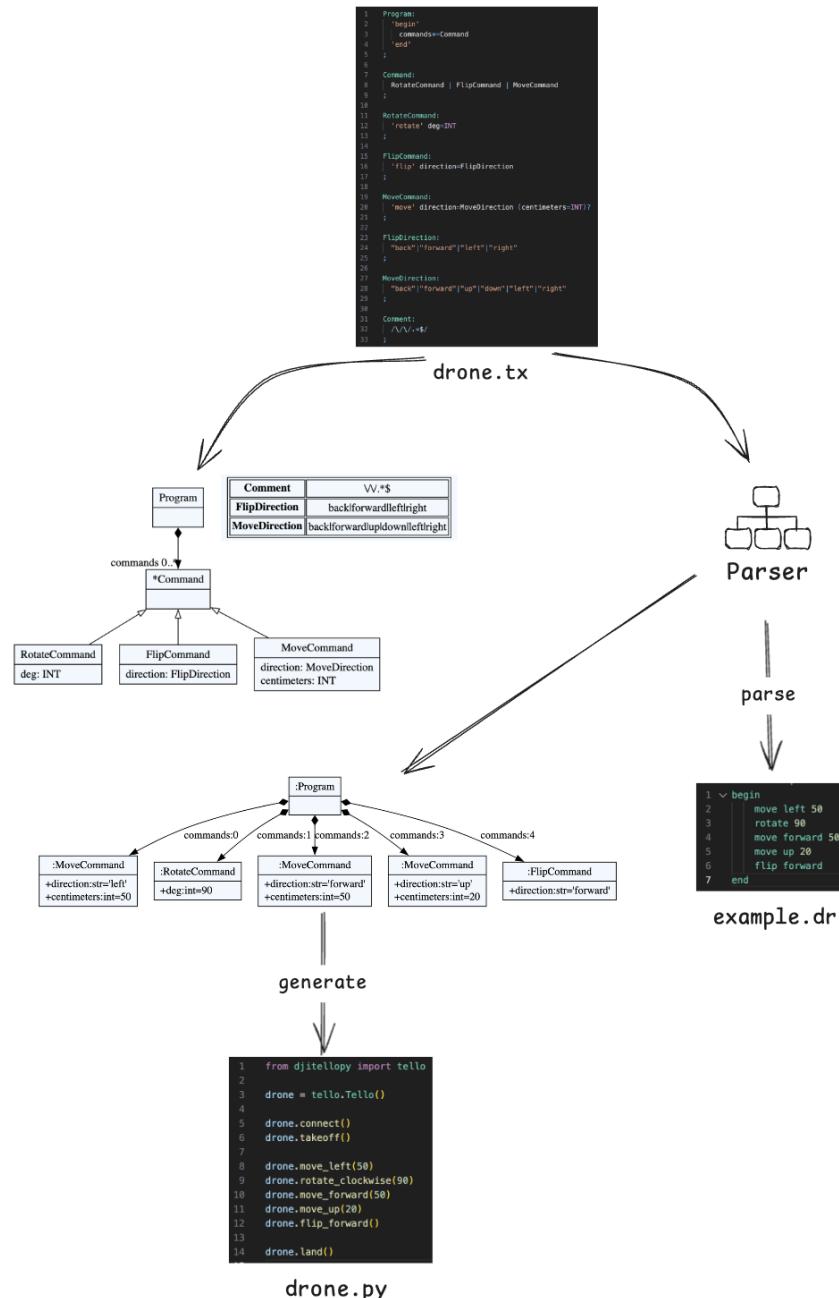
1. Meta-model and Parser are built from Grammar file
2. Parser builds Model during Program parsing
3. Generate code or interpret

Model corresponds to Meta-model

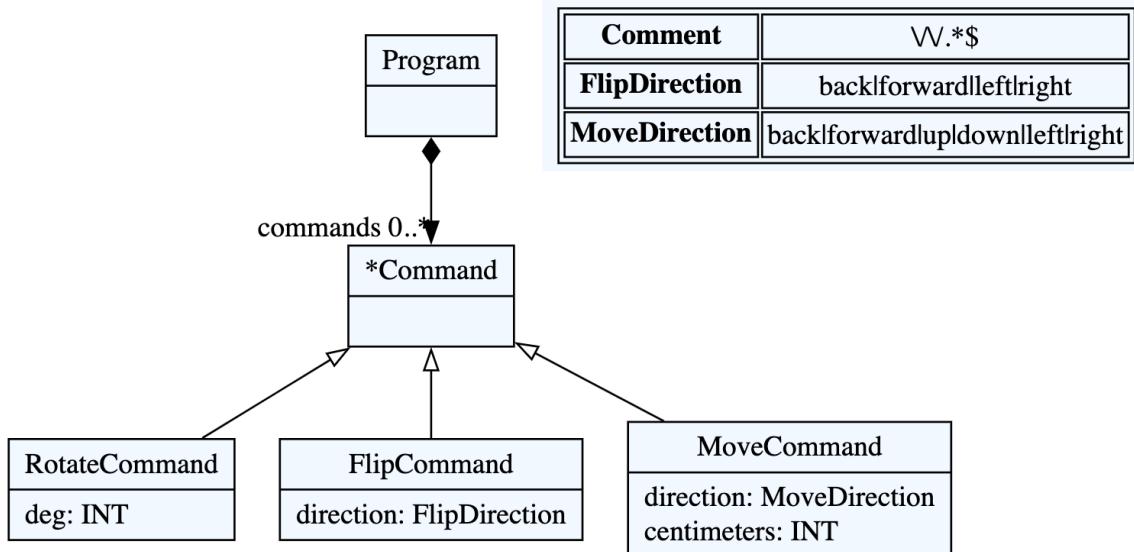


# textX – Drone Example

1. Meta-model and Parser built from the `drone.tx` grammar file
2. Parser builds Model during parsing the `example.dr` file
3. Generate executable Python code in `drone.py` file

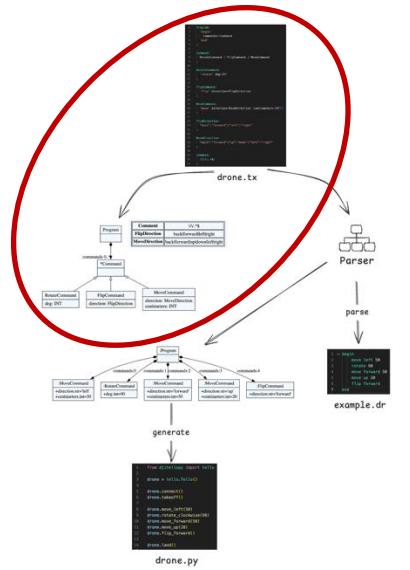


# textX – Grammar and Metamodel

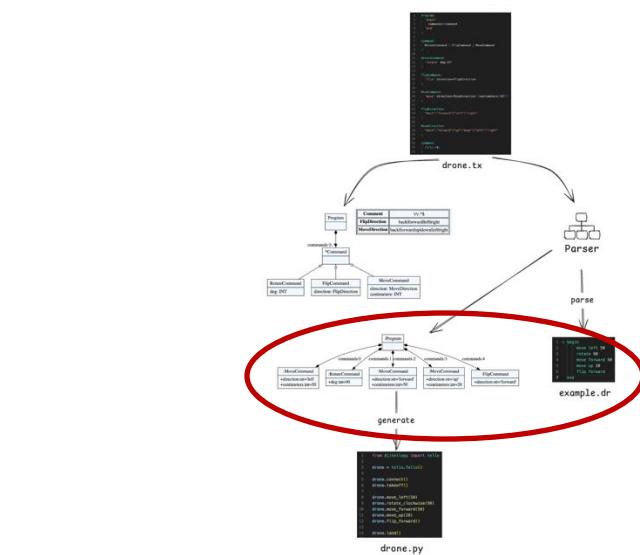
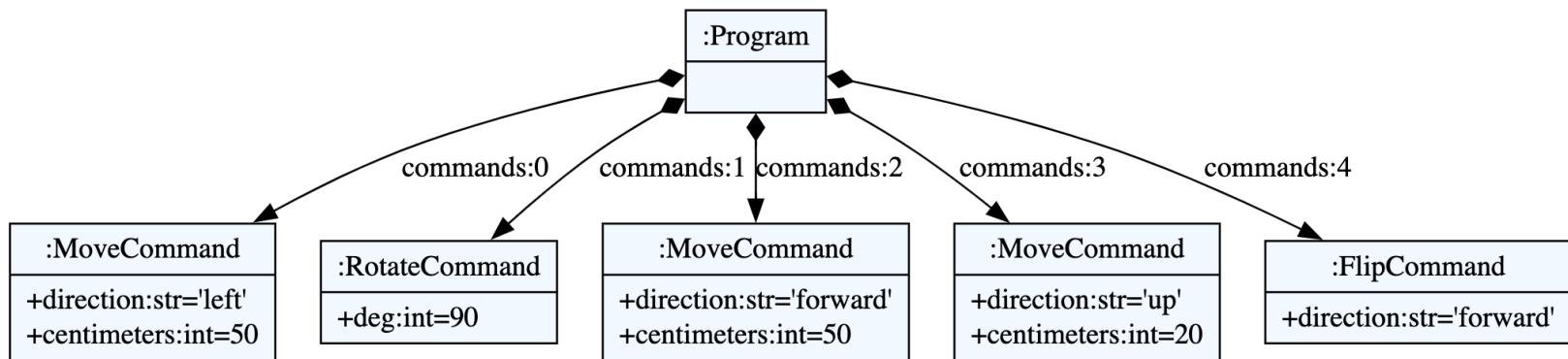


```
1 Program:
2   'begin'
3   | commands*=Command
4   'end'
5 ;
6
7 Command:
8   | RotateCommand | FlipCommand | MoveCommand
9 ;
10
11 RotateCommand:
12   | 'rotate' deg=INT
13 ;
14
15 FlipCommand:
16   | 'flip' direction=FlipDirection
17 ;
18
19 MoveCommand:
20   | 'move' direction=MoveDirection (centimeters=INT)?
21 ;
22
23 FlipDirection:
24   | "back"|"forward"|"left"|"right"
25 ;
26
27 MoveDirection:
28   | "back"|"forward"|"up"|"down"|"left"|"right"
29 ;
30
31 Comment:
32   | /\//.*$/
33 ;
```

drone.tx



# textX – Program and Model



```
1 ✓ begin
2   move left 50
3   rotate 90
4   move forward 50
5   move up 20
6   flip forward
7 end
```

`example.dr`

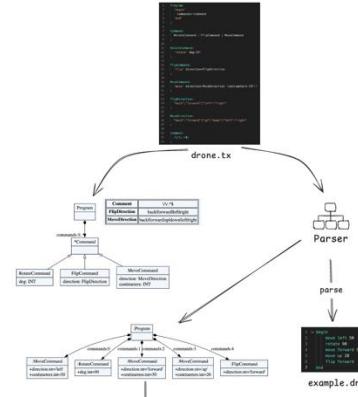
# textX – Code Generation

```
1  from djitellopy import tello
2
3  drone = tello.Tello()
4
5  drone.connect()
6  drone.takeoff()
7
8  {% for command in commands %}
9      {% if command.__class__.__name__ == 'MoveCommand' %} 
10     drone.move_{{command.direction}}({{command.centimeters}})
11     {% endif %}
12     {% if command.__class__.__name__ == 'RotateCommand' %} 
13     drone.rotate_{{'clockwise' if command.deg > 0 else 'counter_clockwise'}}({{command.deg}})
14     {% endif %}
15     {% if command.__class__.__name__ == 'FlipCommand' %} 
16     drone.flip_{{command.direction}}()
17     {% endif %}
18  {% endfor %}
19
20  drone.land()
```

drone.py.jinja

```
1  from djitellopy import tello
2
3  drone = tello.Tello()
4
5  drone.connect()
6  drone.takeoff()
7
8  drone.move_left(50)
9  drone.rotate_clockwise(90)
10 drone.move_forward(50)
11 drone.move_up(20)
12 drone.flip_forward()
13
14 drone.land()
```

drone.py



# textX – Validation from python script

```
from textx import metamodel_from_file

# validate metamodel
metamodel = metamodel_from_file('drone.tx')

# validate model based on metamodel
model = metamodel.model_from_file('example.dr')
```



# textX – Validation from CLI

- Metamodel validation

```
textx check drone.tx
```

- Model validation

- language not registered

```
textx check example.dr --grammar drone.tx
```

- language registered

```
textx check example.dr
```

```
textx check example.dr --language drone
```



# **textX – Other CLI commands**

- List registered languages

```
textx list-languages
```

- List registered generators

```
textx list-generators
```

- Generate code

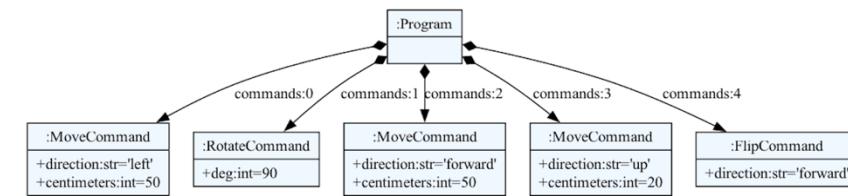
```
textx generate --language Drone --target python --overwrite
```



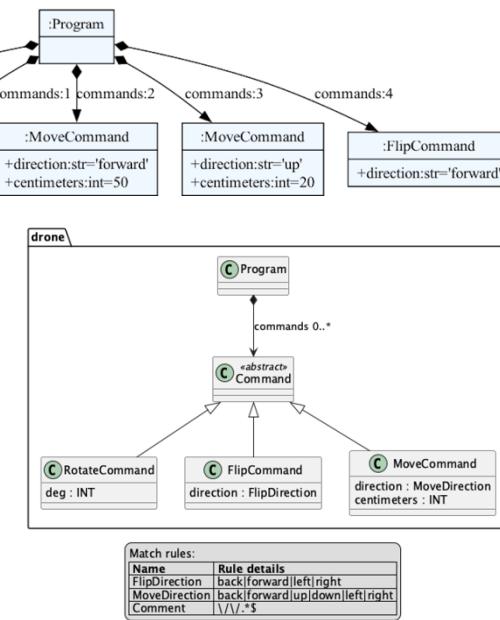
# textX – Visualization

- Visualize model and metamodel

```
textx generate --grammar drone.tx --target dot example.dr  
dot -Tpng -O example.dot
```



```
textx generate drone.tx --target plantuml  
plantuml drone.pu
```



# Web Playground

Motivation, Considerations and Solution



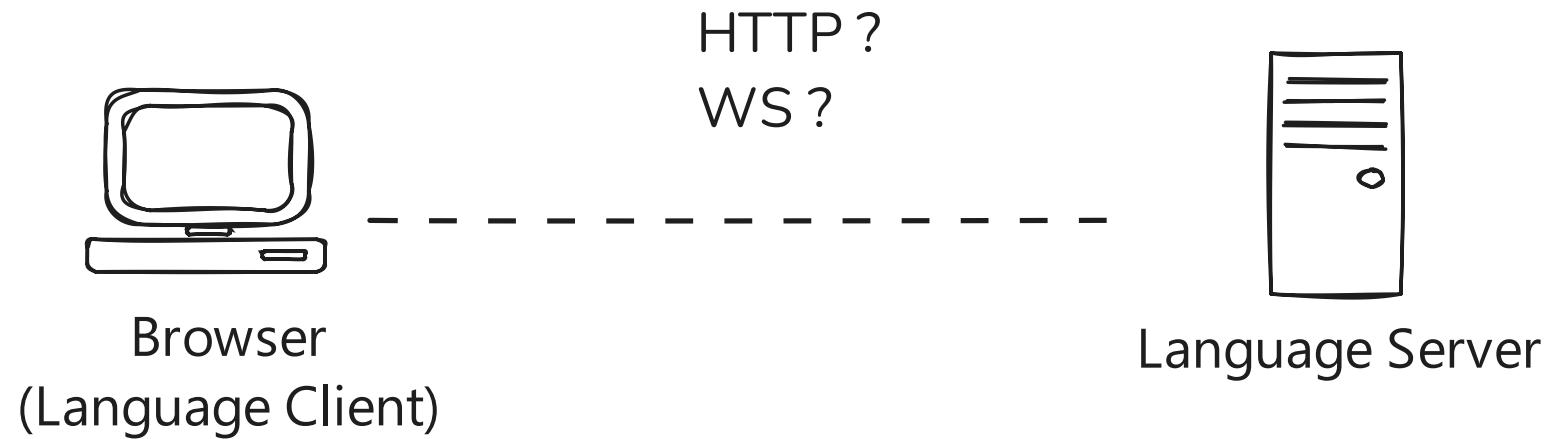
# Web Playground – Motivation

- Trying `textX` includes:
  - Prerequisites - python and pip
  - Creating virtual env (optional)
  - Installing `textX`
  - Running python script or `textX` CLI commands
- Web Playground 



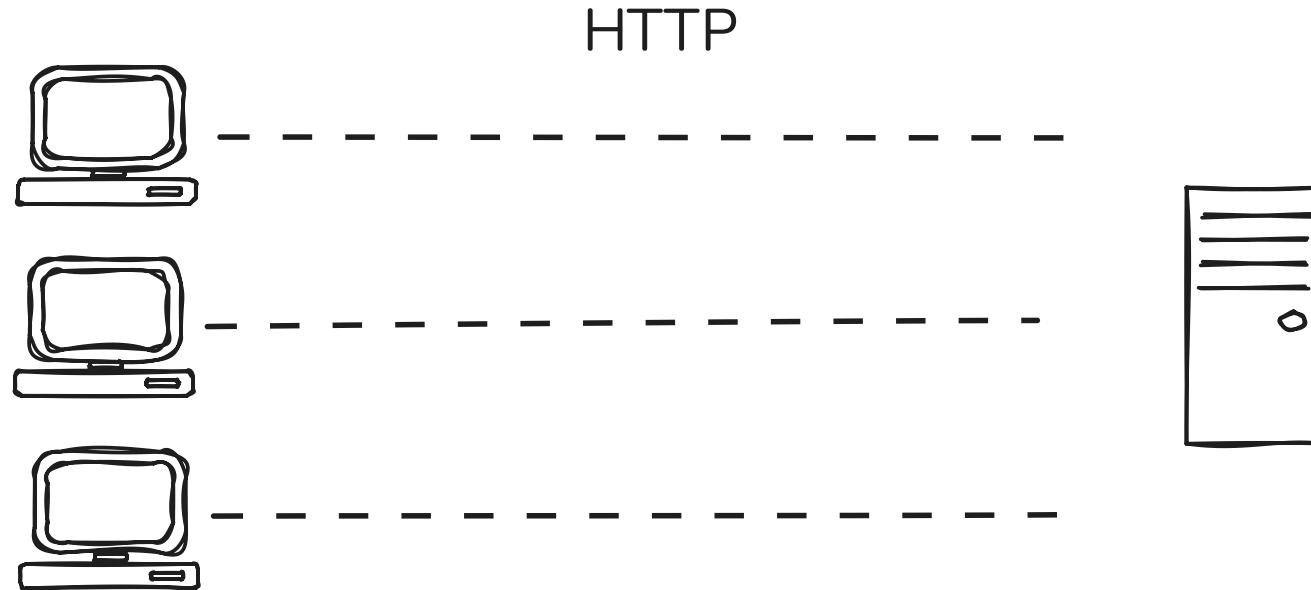
# Web Playground – Considerations

- Language Client and Server architecture and communication



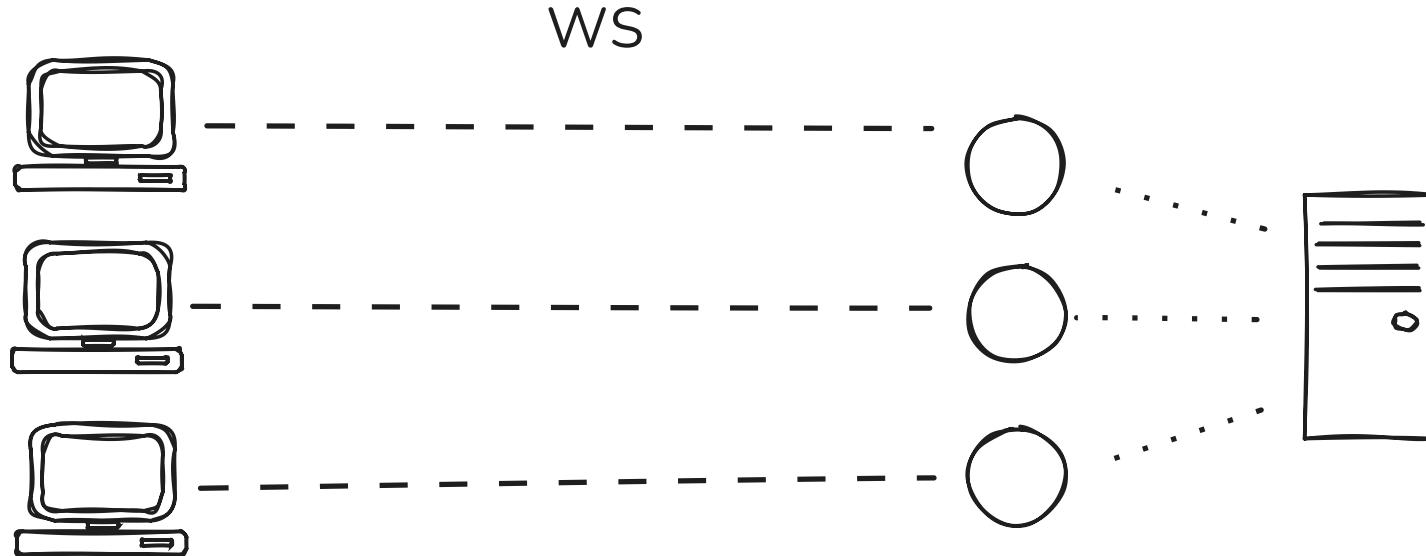
# Web Playground – Considerations

- HTTP connection, manage sessions and documents state



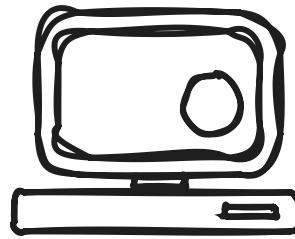
# Web Playground – Considerations

- Separate process per client with WebSocket connection



# Web Playground – Considerations

- Language server and client on the same machine



Download LS and run it?  
Run LS in the browser?



# Web Playground

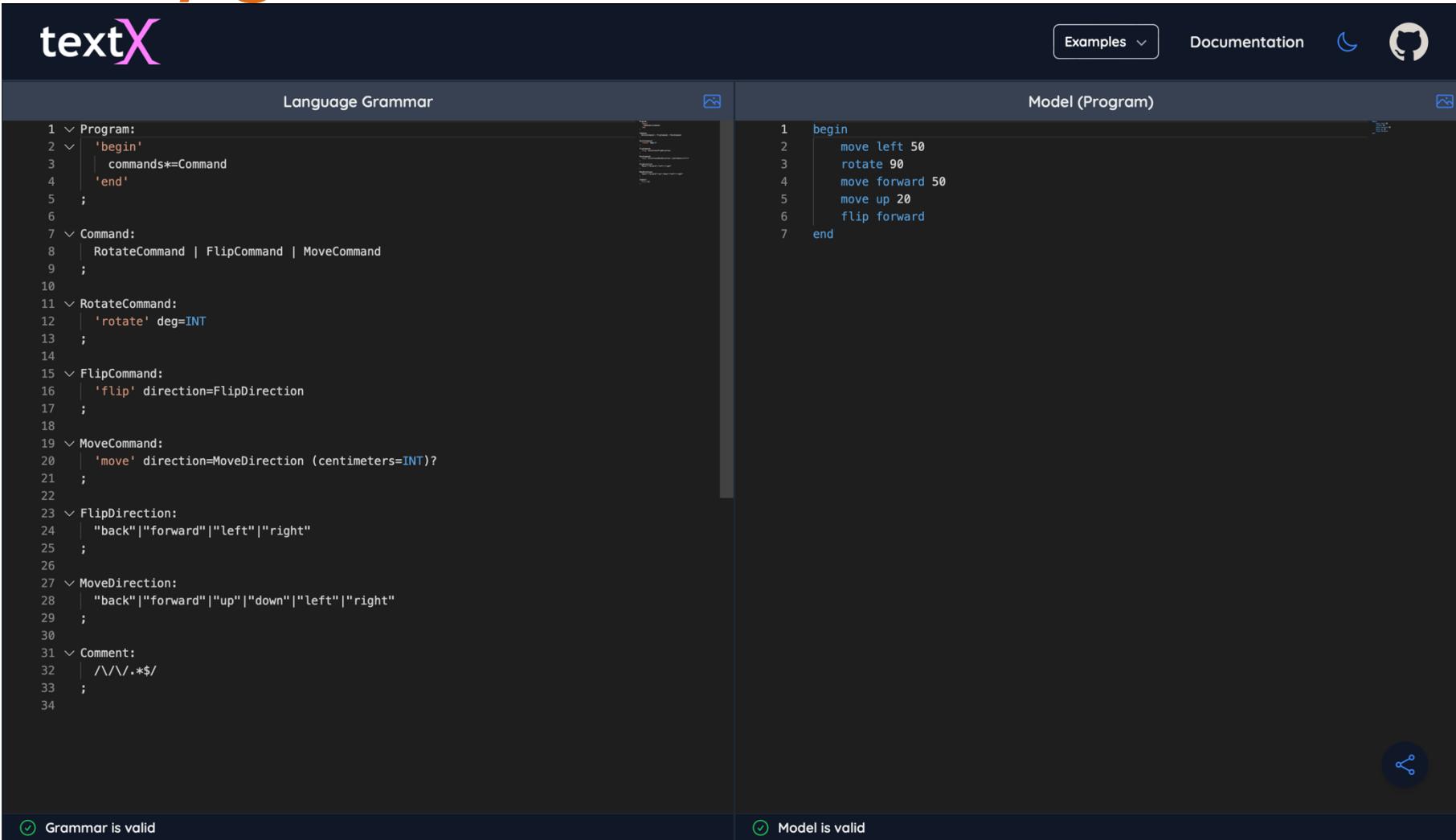
- Created in 2024 by Milan Šović
- Language Server based on [Pygl](#)
- Runs in a Web Worker, using [Pyodide](#)
- Monaco editor
- Language Client based on [monaco-languageclient](#) and [vscode-languageclient](#)

Github: <https://github.com/textX/textx-playground>

Playground: <https://textx.github.io/textx-playground>



# Web Playground



The screenshot shows a web-based playground interface for defining and testing a domain-specific language (DSL) using the textX library.

**Language Grammar:**

```
1 √ Program:
2 √   'begin'
3   | commands*=Command
4   'end'
5 ;
6
7 √ Command:
8   | RotateCommand | FlipCommand | MoveCommand
9 ;
10
11 √ RotateCommand:
12   | 'rotate' deg=INT
13 ;
14
15 √ FlipCommand:
16   | 'flip' direction=FlipDirection
17 ;
18
19 √ MoveCommand:
20   | 'move' direction=MoveDirection (centimeters=INT)?
21 ;
22
23 √ FlipDirection:
24   | "back"|"forward"|"left"|"right"
25 ;
26
27 √ MoveDirection:
28   | "back"|"forward"|"up"|"down"|"left"|"right"
29 ;
30
31 √ Comment:
32   | /\V/.*/$/
33 ;
34
```

**Model (Program):**

```
1 begin
2   move left 50
3   rotate 90
4   move forward 50
5   move up 20
6   flip forward
7 end
```

At the bottom of the interface, there are two status indicators:

- Grammar is valid (green checkmark)
- Model is valid (green checkmark)

# Web Playground

The screenshot shows the textX Web Playground interface. On the left, the **Language Grammar** section displays a hierarchical grammar definition:

```
1 √ Program:  
2 √   'begin'  
3   | commands*=Command  
4   'end'  
5 ;  
6  
7 √ Command:  
8   | RotateCommand | FlipCommand | MoveCommand  
9 ;  
10  
11 √ RotateCommand:  
12   | 'rotate' deg=INT  
13 ;  
14  
15 √ FlipCommand:  
16   | 'flip' direction=FlipDirection  
17 ;  
18  
19 √ MoveCommand:  
20   | 'move' direction=MoveDirection (centimeters=INT)?  
21 ;  
22  
23 √ FlipDirection:  
24   | "back"|"forward"|"left"|"right"  
25 ;  
26  
27 √ MoveDirection:  
28   | "back"|"forward"|"up"|"down"|"left"|"right"  
29 ;  
30  
31 √ Comment:  
32   | /\V/.*/$/  
33 ;  
34
```

On the right, the **Model (Program)** section contains a program:

```
1 begin  
2   move left 50  
3   rotate 90  
4   move forward 50  
5   move up 20  
6   flip forward  
7 end
```

Annotations highlight several UI elements:

- A red box surrounds the **Examples** dropdown menu.
- Two red circles with arrows point from the **Language Grammar** and **Model (Program)** sections to a red **Visualize** button located below the **Model (Program)** section.
- A red box surrounds the **Status Bar**.
- A red box surrounds the **Share** icon.
- At the bottom, two status messages are shown: **Grammar is valid** and **Model is valid**.

# Web Playground – Features

- Grammar and Program definition with instant validation
- Basic syntax highlighting
- Grammar and Program visualization
- Light and dark theme
- Examples
- Share

[Share link to Drone example](#)



# VS Code Extension



# VS Code Extension

- Created by Daniel Elero in 2018
- Contains:
  - **textX Language Server** (based on [Pygls](#))
  - **VS Code Extension**

Github: <https://github.com/textX/textX-LS>

PyPi: <https://pypi.org/project/textx-ls-server/>

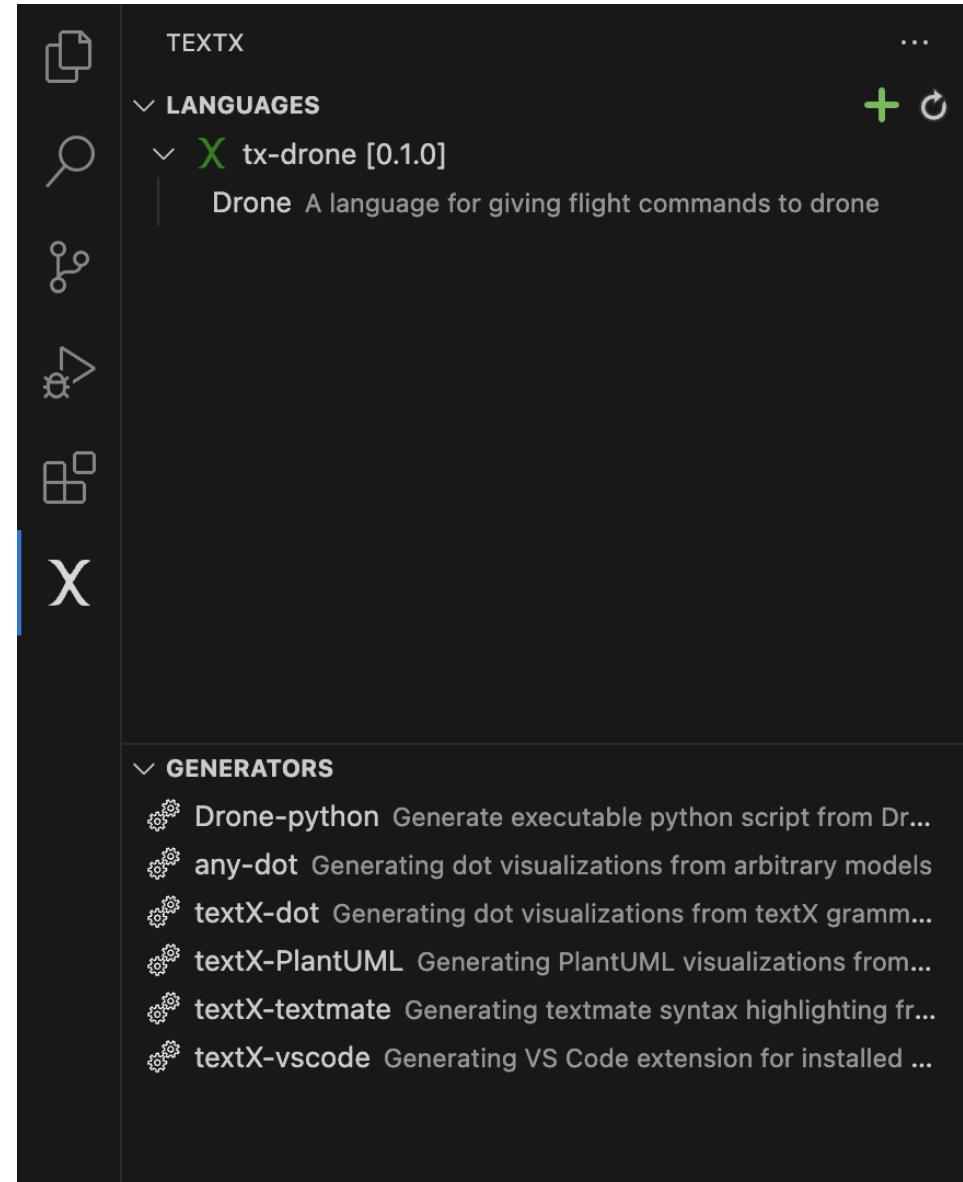
VS Code Marketplace:

<https://marketplace.visualstudio.com/items?itemName=textX.textX>



# VS Code Extension – Sidebar

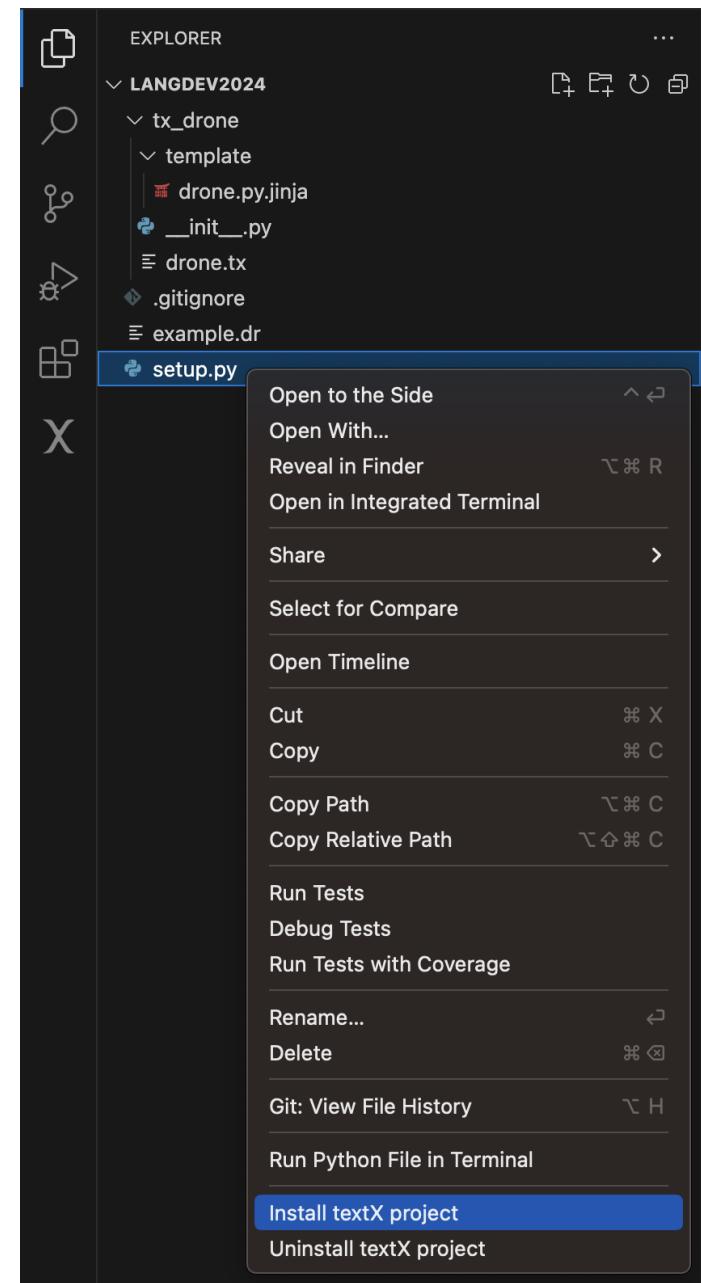
- Project installation from wheel file
- Show and Refresh projects with registered languages
- Show registered generators



# VS Code Extension

- Project installation from python package configuration file
- It will be installed in extension's virtual environment

```
textx_ls_core      0.2.0
textx_ls_server    0.2.0
tx-drone          0.1.0
```



# VS Code Extension

- Grammar and Program instant validation (error reporting)
- Syntax highlighting

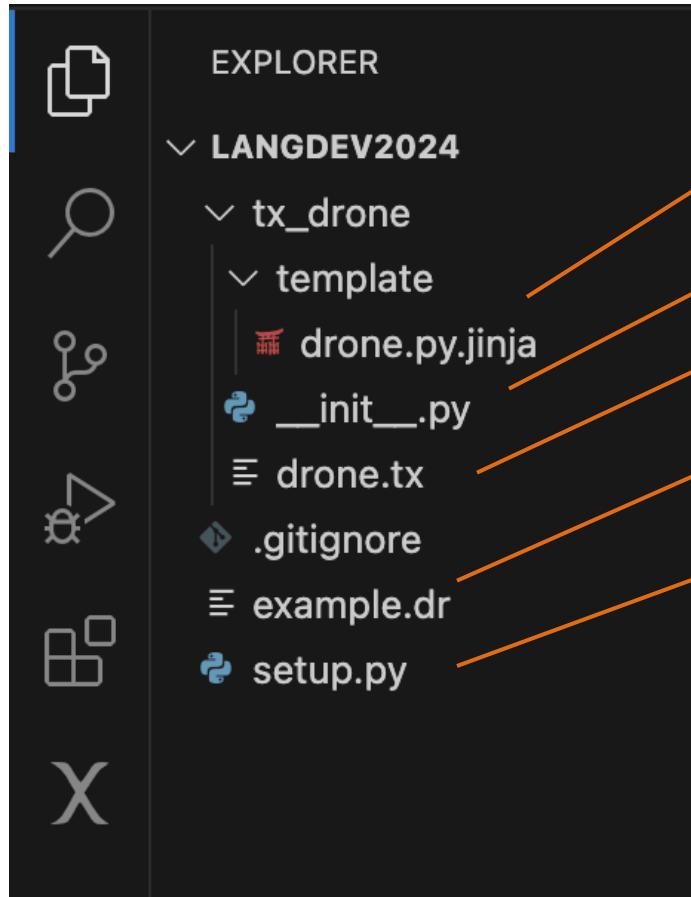
```
tx_drone > └── drone.tx
1   Program:
2   |   'begin'
3   |   commands*=Command
4   |   'end'
5   ;
6
7   Command:
8   |   RotateCommand | FlipCommand | MoveCommand
9   ;
10
11  RotateCommand:
12  |   'rotate' deg=INT
13  |
14  |   Expected '=' or '*=' or '+=' or '?=' or '*' or '?' or '+' or '#' or '-' or
15  |   View Problem (⌘.) No quick fixes available
16  FlipCommand:
17  |   'flip' direction=FlipDirection
18  ;
```

```
└── example.dr
1   begin
2
3
4
5   |   mov
6   |   Expected 'rotate' or 'flip' or 'move' or 'end'
7   |   View Problem (⌘.) No quick fixes available
8
9   end
```

# Drone Example Demo



# Drone Example



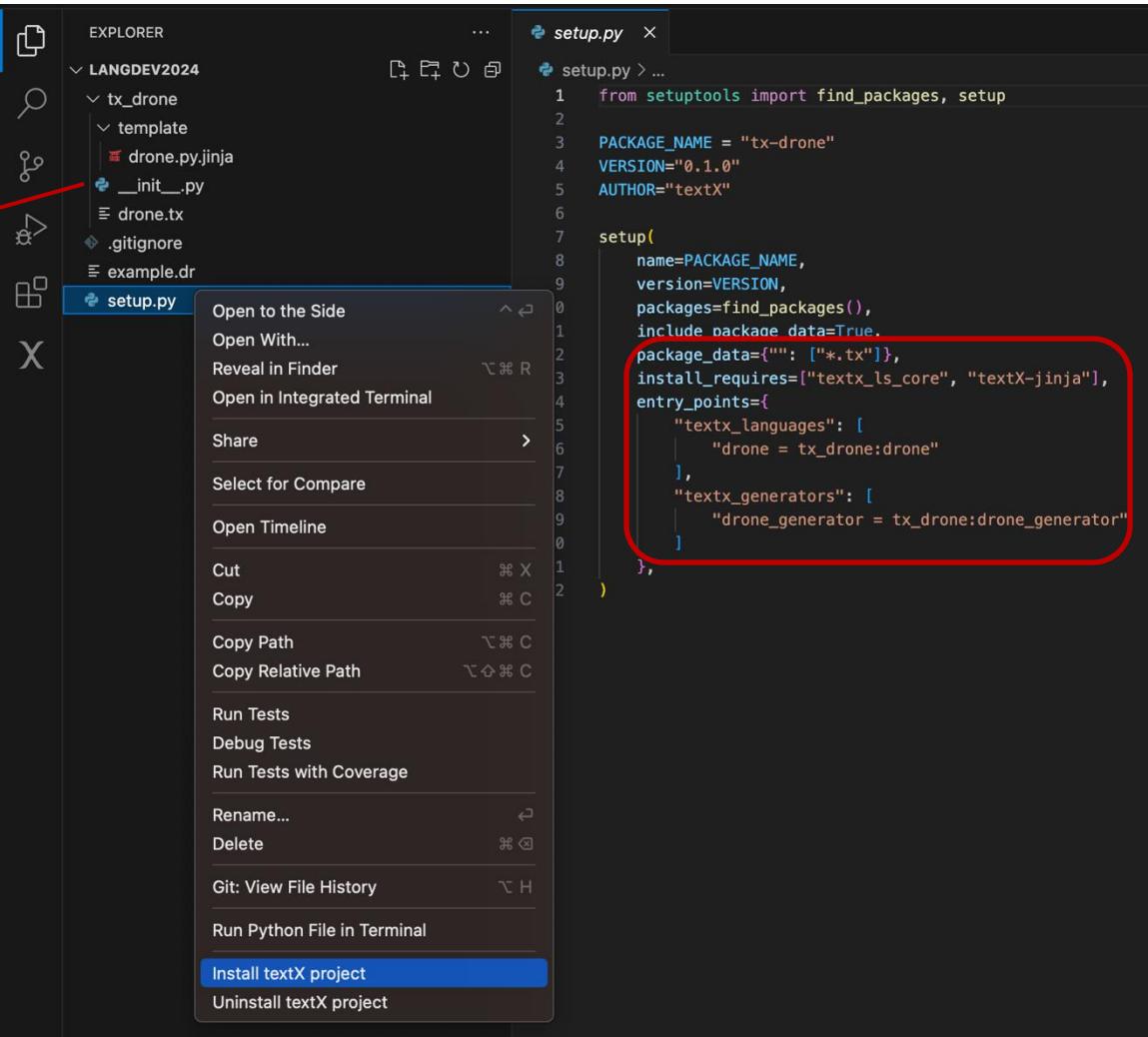
- Template
- Language and generator registration
- Grammar
- Program
- Project config file

GitHub: <https://github.com/textX/langdev2024>

# Drone Example

- Language and generator registration

```
1  from os.path import dirname, join
2
3  from textx import generator, language, metamodel_from_file
4  from textxjinja import textx_jinja_generator
5
6
7  @language("Drone", ".dr")
8  def drone():
9      "A language for giving flight commands to drone"
10     return metamodel_from_file(join(dirname(__file__), "drone.tx"))
11
12
13 @generator('Drone', 'python')
14 def drone_generator.metamodel(model, output_path, overwrite, debug):
15     "Generate executable python script from Drone model"
16
17     current_dir = dirname(__file__)
18     templates_path = join(current_dir, 'template')
19     default_output_path = join(current_dir, '..', 'dist')
20
21     context = {
22         'commands': model.commands
23     }
24
25     textx_jinja_generator(templates_path, output_path or default_output_path, context, overwrite)
```



The screenshot shows a code editor with the `setup.py` file open. The `entry_points` section is highlighted with a red box:

```
1  from setuptools import find_packages, setup
2
3  PACKAGE_NAME = "tx-drone"
4  VERSION="0.1.0"
5  AUTHOR="textX"
6
7  setup(
8      name=PACKAGE_NAME,
9      version=VERSION,
10     packages=find_packages(),
11     include_package_data=True,
12     package_data={"": ["*.tx"]},
13     install_requires=["textx_ls_core", "textX-jinja"],
14     entry_points={
15         "textx_languages": [
16             "drone = tx_drone:drone"
17         ],
18         "textx_generators": [
19             "drone_generator = tx_drone:drone_generator"
20         ]
21     },
22 )
```

# Drone Example

- Generated code execution

```
begin
  move left 50
  rotate 90
  move forward 50
  move up 20
end
```

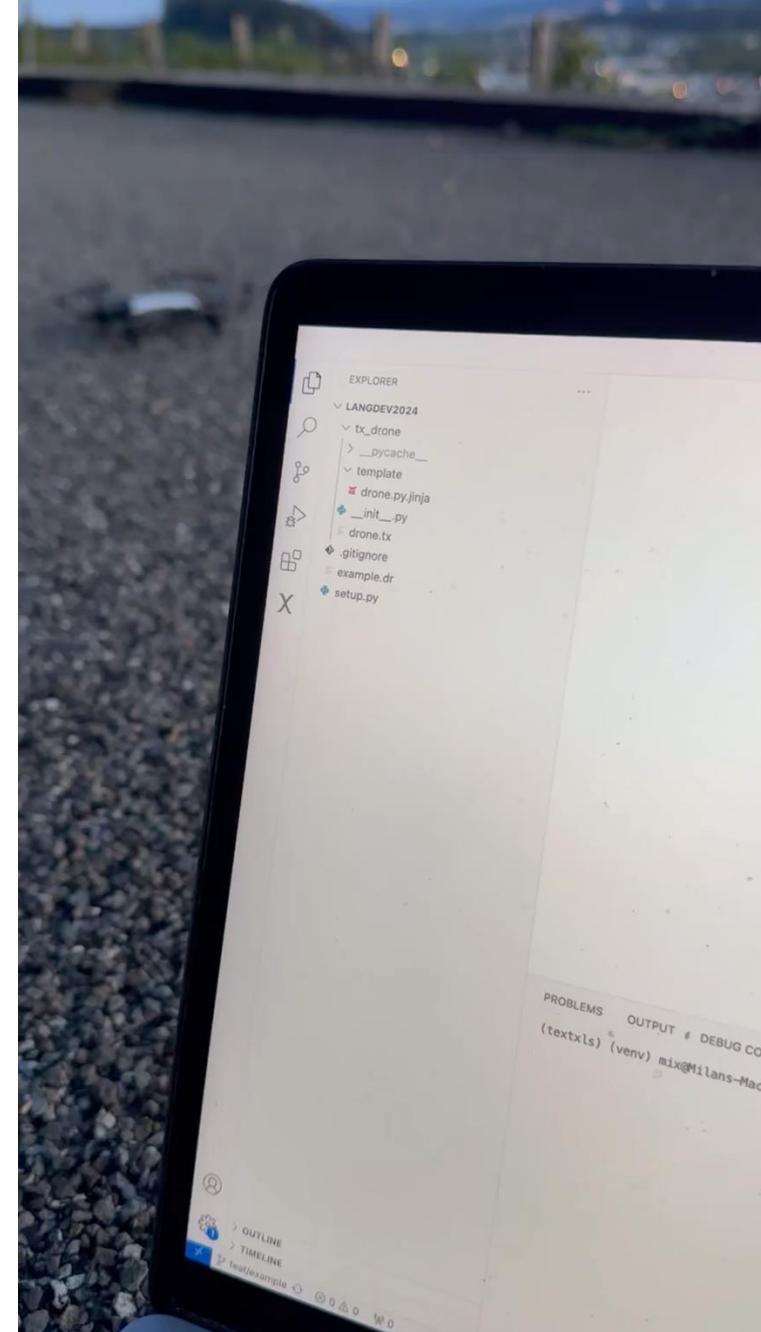
```
from djitellopy import tello

drone = tello.Tello()

drone.connect()
drone.takeoff()

drone.move_left(50)
drone.rotate_clockwise(90)
drone.move_forward(50)
drone.move_up(20)

drone.land()
```



# Summary

Latest Updates and Next Steps



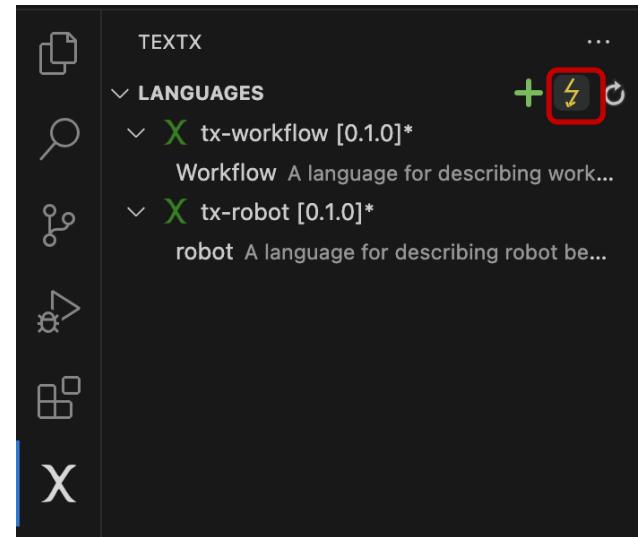
# Summary – Latest Updates

- Created `textX` Web Playground
- New `textX LS` version:
  - upgraded python, `textX` and other dependencies versions
  - packages `textx-ls-core 0.2.0` and `textx-ls-server 0.2.0`
- New VS Code Extension version – `textX v0.2.0`



# Summary – Next Steps

- VS Code Extension improvements:
  - project scaffolding
  - run code generators from tree view
  - run textX LS in VS Code inside Pyodide (no Python dependency)
- Playground improvements:
  - replace custom Pyglsl implementation with textX LS



JGBX



# Q&A

textX Organization | <https://github.com/textX>

Presentation and Demos | <https://github.com/textX/langdev2024>

# Appendix – textX Related Repos

- [textX](#) – language
- [textX-LS \(upgraded\)](#) – language server and VC Code extension
- [textx-playground \(new\)](#) – web playground
- [textX-jinja](#) – template-based code generation from textX models
- [textX-dev](#) – project scaffolding
- [textX-lang-questionnaire](#) – questionnaire DSL, used by textX-dev

**textX**

